

FTD Operator Name				
• FTD Qualification Level	□ FTD Level 1		□ FTD Level 2	
• FTD Qualification Type	□ Initial Qualification	□ Qualification renewal	□ Modifications	□ Re-location
• FTD Manufacturer Name				
• FTD Serial No				
• FTD Qualification Number				
• FTD Qualification Expiry Date				

#### A. Flight Training Devices (FTD) general technical requirements.

Qual. Level	Concerci Technical Dequirements	Result			
Qual. Level	General Technical Requirements	YES	NO		

Type specific with at least 1 system fully represented.		
Enclosed or open flight deck.		
Choice of systems simulated is the responsibility of the organization seeking approval or re approval for the course.		
The airplane system simulated shall comply with the relevant subjective and objective tests relevant to that system.		
	Type specific with at least 1 system fully represented.         Enclosed or open flight deck.         Choice of systems simulated is the responsibility of the organization seeking approval or re approval for the course.         The airplane system simulated shall comply with the relevant subjective and objective tests relevant to that system.	Type specific with at least 1 system fully represented.       Image: Comparison of the system fully represented.         Enclosed or open flight deck.       Image: Comparison of the system simulated is the responsibility of the organization seeking approval or re approval for the course.         The airplane system simulated shall comply with the relevant subjective and objective tests relevant to that system.

	Type specific device with all applicable systems fully represented.	
	An enclosed flight deck with an onboard instructor station.	
	Type specific or generic flight dynamics (but shall be representative of aircraft performance)	
FTD Level 2	Primary flight controls which control the flight path and be broadly representative of airplane control characteristics	
	Significant sounds	
	Control of atmospheric conditions	
	Navigation Data Base sufficient to support simulated airplane systems	

Remarks					

Inspector Name	Date	Signature
Oualified FTD ( ) Assessor Name	Date	Signature



#### **B.** Flight Training Devices (FTD) Qualification Requirements.

General

1

This checklist describes the minimum Flight Training Devices (FTD) requirements for qualifying devices to the required Qualification Levels. Certain requirements included in this section shall be supported with a statement of compliance (SOC) and, in some designated cases, an objective test. The SOC will describe how the requirement was met. The test results shall show that the requirement has been attained. In the following tabular listing of FSTD standards, statements of compliance are indicated in the compliance column.

Requirements	FTD	Level	Statement of Compliance	YES		
	1	2	Statement of Comphance	YES	NO	

cockpit/flight sufficiently deck А enclosed to exclude distraction, which Х а will replicate that of the airplane or class of airplane simulated A full-size panel of replicated system(s) The use of electronically displayed images with which will have actuation of controls and physical overlay incorporating operable b Х Х switches that replicate those of the switches, knobs, buttons replicating airplane airplane simulated instruments panels may be acceptable Crewmembers' seats shall be provided with sufficient adjustment to allow the occupant to achieve the design eve с reference position appropriate to the Х airplane or class of airplane and for the visual system to be installed to align with that eye position. Circuit breakers that affect procedures and/or result in observable cockpit Х Х d indications properly located and functionally accurate For FTD Levels 1 and 2 aerodynamic modeling Flight dynamics model that accounts for sufficient to permit accurate systems operation various combinations of drag and thrust and indication is acceptable. normally encountered in flight corresponding to actual flight conditions, Х including the effect of change in airplane Х e attitude, sideslip, thrust, drag, altitude, temperature, gross weight, moments of inertia, center of gravity location, and configuration. All relevant instrument indications involved in the simulation of the applicable airplane shall automatically f respond to control movement by a flight Х Х crewmember or induced disturbance to the simulated airplane; e.g., turbulence or wind shear For FTD Level 2 lighting environment shall be Lighting environment for panels and Х instruments shall be sufficient for the Х as per airplane g operation being conducted.



	Requirements		Requirements FID Level Statement of Compliance		Statement of Compliance	YE	
	Keyun ements	1	2	Statement of Compliance	YES	NO	
h	Communications, navigation, and caution and warning equipment corresponding to that installed in the applicant's airplane with operation within the tolerances	X	x	For FTD 1 applies where the appropriate systems are replicated			
i	nor the applicable airborne equipment Navigational data with the corresponding approach facilities. Navigation aids should be usable within range without restriction.	X	X	For FTD 1 applies where navigation equipment is replicated. For all FFSs and FTDs 2 where used for area or airfield competence training or checking, navigation data should be updated within 28 days			
j	In addition to the flight crewmember duty stations, three suitable seats for the instructor, delegated examiner and GACA inspector. GACA will consider options to this standard based on unique cockpit configurations. These seats shall provide adequate vision to the pilot's panel and forward windows. Observer seats need not represent those found in the airplane but in the case of FSTDs fitted with a motion system, the seats shall be adequately secured to the floor of the FSTD, fitted with positive restraint devices and be of sufficient integrity to safely restrain the occupant during any known or predicted motion system excursion	X	X	For FTDs and FNPT's suitable seating arrangements for the Instructor and Examiner or GACA Inspector should be provided.			
k	FSTD systems shall simulate applicable airplane system operation, both on the ground and in flight. Systems shall be operative to the extent that all normal, abnormal, and emergency operating procedures can be accomplished	X	x	For FTD Level 1, applies where system is simulated			
1	Instructor controls shall enable the operator to control all required system variables and insert abnormal or emergency conditions into the airplane systems	X	X	<ul> <li>Where applicable and as required for training the following shall be available :</li> <li>Position and flight freeze.</li> <li>A facility to enable the dynamic plotting of the flight path on approaches, commencing at the final approach fix, including the vertical profile</li> <li>Hard copy of map and approach plot</li> </ul>			
m	Control forces and control travel shall correspond to that of the replicated airplane. Control forces shall react in the same manner as in the airplane under the same flight conditions		X	For FTD Level 2 Control forces and control travel should correspond to that of the replicated airplane with CT&M. It is not intended that the device should be flown manually other than for short periods when the autopilot is temporarily disengaged			



Requirements		FTD Level		Statement of Compliance		YES	
	Kequitements	1	2	Statement of Compliance	YES	NO	
n	Instructor controls for environmental effects including wind speed and direction shall be provided	X	X	For FTDs environment modeling sufficient to permit accurate systems operation and indication			
0	Computer capacity, accuracy, resolution, and dynamic response shall be sufficient to fully support the overall fidelity, including its evaluation and testing	X	X	Statement of Compliance required.			
р	One of the following two methods is acceptable as a means to prove compliance: (1) Transport Delay: A transport delay test may be used to demonstrate that the FSTD system response does not exceed 150 milliseconds. This test shall measure all the delay encountered by a step signal migrating from the pilot's control through the control loading electronics and interfacing through all the simulation software modules in the correct order, using a handshaking protocol, finally through the normal output interfaces to the motion system, to the visual system and instrument displays. (2) Latency: The visual system, flight deck instruments and initial motion system response shall respond to abrupt pitch, roll and yaw inputs from the pilot's position within 150 milliseconds of the time, but not before the time, when the airplane would respond under the same conditions	X	X	Tests required. For Level 'A' & 'B' FFSs, and applicable systems for FTDs, FNPTs and BITDs the maximum permissible delay is 300 milliseconds			
q	Timely and permanent update of hardware and programming subsequent to airplane modification sufficient for the Qualification Level sought	X	X				
r	Daily pre-flight documentation either in the daily log or in a location easily accessible for review is required						

# 2 Sound System a Significant flight deck sounds which result from pilot actions corresponding to those of the airplane or class of airplane X



Rema	arks

Inspector Name	Signature	Date
Qualified FTD ( ) Assessor Name	Signature	Date



## C. Flight Training Devices (FTD) Functions and Subjective Tests.

No	Table of Eurotians and Subjective Tests		FTD		sult
INO.	Table of Functions and Subjective Tests	1	2	YES	NO
a	PREPARATION FOR FLIGHT				
	(1) Preflight. Accomplish functions check of all switches, indicators, systems, and equipment at all				
	crewmembers' and instructors' stations and determine that;				
	simulated	$\checkmark$	$\checkmark$		
b	SURFACE OPERATIONS (PRE-TAKE-OFF)				
	(1) Engine Start				
	(a) Normal start	$\checkmark$	$\checkmark$		
	(b) Alternate start procedures	$\checkmark$	$\checkmark$		
	(c) Abnormal starts and shutdowns (hot start, hung start, tail pipe fire, etc.)	$\checkmark$	$\checkmark$		
			-		
с	TAKE-OFF				
	(1) Normal				
	(a) Airplane/engine parameter relationships	$\checkmark$	$\checkmark$		
	(b) Acceleration characteristics (not associated with motion)	$\checkmark$	$\checkmark$		
	(c) Nose wheel and rudder steering	$\checkmark$	$\checkmark$		
d	CLIMB				
	(1) Normal	$\checkmark$	$\checkmark$		
	(2) One or more engines inoperative	$\checkmark$	$\checkmark$		
	(3) Other	$\checkmark$	$\checkmark$		
			-		
e	CRUISE				
	(1) Performance characteristics (speed vs. power)	$\checkmark$	$\checkmark$		
	(2) High altitude handling	$\checkmark$	$\checkmark$		
	(3) High Mach number handling (Mach tuck, Mach buffet) and recovery (trim change)	$\checkmark$	$\checkmark$		
	(4) High IAS handling	$\checkmark$	$\checkmark$		
·					
f	MANOEUVRES				
	(1) High angle of attack, approach to stalls, stall warning, buffet, and g-break (take-off, cruise, approach, and landing configuration)	$\checkmark$	$\checkmark$		
	(2) Flight envelope protection (high angle of attack, bank limit, over speed, etc)	$\checkmark$	$\checkmark$		
	(3) Turns with/without speed brake/spoilers deployed	$\checkmark$	$\checkmark$		
	(4) In flight engine shutdown and restart (assisted and windmill)	$\checkmark$	$\checkmark$		
	(5) Maneuvering with one or more engines inoperative, as appropriate	$\checkmark$	$\checkmark$		
	(6) Specific flight characteristics (e.g. direct lift control)	$\checkmark$	$\checkmark$		
	(7) Flight control system failures, reconfiguration modes, manual reversion and associated handling	$\checkmark$	$\checkmark$		
	(8) Other	$\checkmark$	$\checkmark$		



No	Table of Functions and Subjective Tests		FID		Result	
110.	Table of Functions and Subjective Tests	1	2	YES	NO	
			-			
g	DESCENT	L				
	(1) Normal	$\checkmark$	$\checkmark$			
	(2) Maximum rate (clean and with speed brake, etc.)	$\checkmark$	$\checkmark$			
	(3) Flight control system failures, reconfiguration modes, manual reversion and associated	$\checkmark$	$\checkmark$			
	handling			ļ		
	(4) Other	$\checkmark$	$\checkmark$		<u> </u>	
Ŀ			T	<u> </u>	1	
n	INSTRUMENT APPROACHES AND LANDING			<u> </u>		
	Only those instrument approach and landing tests relevant to the simulated airplane type					
	or class should be selected from the following list, where tests should be made with limiting					
	Director					
	(1) Provision					
	(a) CAT I/CPAS (II S/MIS) published approaches					
	(a) CAT I/ODAS (ILS/MLS) published apploaches	$\checkmark$		<u> </u>		
	A. Manual approach with/without flight director including landing	•	• •			
	B. Autophol/auto infolle coupled approach and manual landing	•	•			
	C. Manual approach to DH and G/A all engines	• 	v (			
	D. Manual one engine out approach to DH and G/A	v	v (	·		
	E. Autopilot/auto throttle coupled approach, one engine out to DH and G/A	v	V			
	F. Approach and landing with minimum/standby electrical power         (b) CAT II/GBAS (ILS/MLS) published approaches					
				ļ		
	A. Autopilot/auto throttle coupled approach to DH and landing	✓	✓			
	B. Autopilot/auto throttle coupled approach to DH and G/A	✓	√			
	C. C Auto coupled approach to DH and manual G/A	$\checkmark$	$\checkmark$			
	(c) CAT III/GBAS (ILS/MLS) published approaches	<u> </u>				
	A. Autopilot/auto throttle coupled approach to land and rollout	$\checkmark$	$\checkmark$			
	B. Autopilot/auto throttle coupled approach to DH/Alert Height and G/A	$\checkmark$	$\checkmark$			
	C. Autopilot/auto throttle coupled approach to land and rollout with one engine out	$\checkmark$	$\checkmark$			
	D. Autopilot/auto throttle coupled approach to DH/Alert Height and G/A with one	$\checkmark$	$\checkmark$			
	engine out					
	(2) Non-precision	<u> </u>				
	(a) NDB	$\checkmark$	$\checkmark$			
	(b) VOR, VOR/DME, VOR/TAC	$\checkmark$	$\checkmark$			
	(c) RNAV (GNSS)	$\checkmark$	$\checkmark$			
	(d) ILS LLZ (LOC), LLZ(LOC)/BC	$\checkmark$	$\checkmark$			
	NOTE: If Standard Operating Procedures are to use autopilot for non-precision approaches,					
	then these should be evaluated	L				
i	VISUAL APPROACHES (SEGMENT) AND LANDINGS.	. <u> </u>	Not a	pplicab	le	
•	MISSED A DDDO A CH		1	<u> </u>	<u> </u>	
J	MISSED APPKUACH					
		. v	· ·		4	



No. Table of Functions and Subjective Tests		D Res		sult	
No.	1 able of Functions and Subjective Tests	1	2	YES	NO
k	SURFACE OPERATIONS (POST LANDING)				
	(1) Landing roll and taxi				
	(a) Spoiler operation	✓	$\checkmark$		
	(b) Reverse thrust operation	$\checkmark$	$\checkmark$		
	(c) Directional control and ground handling, both with and without reverse thrust	$\checkmark$	$\checkmark$		
	(d) Brake operation, to include auto-braking system where applicable	$\checkmark$	$\checkmark$		
	(e) Other	$\checkmark$	$\checkmark$		
1	ANY FLIGHT PHASE				
	(1) Airplane and power plant systems operation				
	(a) Air conditioning and pressurization (ECS)	$\checkmark$	$\checkmark$		
	(b) De-icing/anti-icing	$\checkmark$	$\checkmark$		
	(c) Auxiliary power plant/auxiliary power unit (APU)	$\checkmark$	$\checkmark$		
	(d) Communications	$\checkmark$	$\checkmark$		
	(e) Electrical	$\checkmark$	$\checkmark$		
	(f) Fire and smoke detection and suppression	$\checkmark$	$\checkmark$		
	(g) Flight controls (primary and secondary)	$\checkmark$	$\checkmark$		
	(h) Fuel and oil, hydraulic and pneumatic	$\checkmark$	$\checkmark$		
	(i) Landing gear	$\checkmark$	$\checkmark$		
	(i) Landing gear (j) Oxygen (k) Power plant (l) Airborne rader		$\checkmark$		
	(k) Power plant (k) Airborne reder		$\checkmark$		
	(l) Airborne radar		$\checkmark$		
	(l) Airborne radar (m) Autopilot and Flight Director		$\checkmark$		
	<ul> <li>(i) Autopilot and Flight Director</li> <li>(n) Collision avoidance systems. (e.g., GPWS, TCAS)</li> </ul>		$\checkmark$		
	(o) Flight control computers including stability and control augmentation	$\checkmark$	$\checkmark$		
	(p) Flight display systems	$\checkmark$	$\checkmark$		
	(q) Flight management computers	$\checkmark$	$\checkmark$		
	(r) Head-up guidance, head-up displays	$\checkmark$	$\checkmark$		
	(2) Airborne procedures				
	(a) Holding	$\checkmark$	$\checkmark$		
	(b) Air hazard avoidance. (Traffic, weather)	$\checkmark$	$\checkmark$		
	(c) Wind shear	$\checkmark$	$\checkmark$		
	(3) Engine shutdown and parking				
	(a) Engine and systems operation	$\checkmark$	$\checkmark$		
	(b) Parking brake operation	$\checkmark$	$\checkmark$		
	(4) Other as appropriate including effects of wind	$\checkmark$	$\checkmark$		
m	VISUAL SYSTEM.		Not a	pplicab	le
n	MOTION EFFECTS.		Not a	pplicab	le
0	SOUND SYSTEM.		Not a	pplicab	le
р	SPECIAL EFFECTS.		Not a	pplicab	le
T.		1			



#### GACAR PART - 60

**NOTE** -It is accepted that tests will only apply to FTD Level 1 if that system and flight condition is simulated. It is intended that the tests listed below should be conducted in automatic flight. Where automatic flight is not possible and pilot manual handling is required, the FTD shall be at least controllable to permit the conduct of the flight.

Rema	arks

Inspector Name	Date	Signature

Qualified FTD (	) Assessor Name	Date	Signature

## D. Flight Training Devices (FTD) Validation Test.

<b>1.</b> P	ERFORMANCE						
NI-	Testa	Tolonomoo	Flight	FTD	COMMENTS	Res	ult
INO	Tests	Tolerance	Conditions	1 2	COMMENTS	YES	NO
					It is accepted that tests and associated		
я					tolerances will only apply to a Level 1		
a					FTD if that system or flight condition		
					is simulated.		
	TAXI				Not applicable		
					•		J I



<b>1.</b> P	ERFORMANCE						
NI-	Testa	Tasta	Flight	FTD	COMMENTS	Result	
INO	Tests	Tolerance	Conditions	1 2		YES	NO

	TAKE-OFF						
						Note-All commonly used take-off flap settings should be demonstrated at least once either in minimum un-stick speed (1b3), normal take-off (1b4), and critical engine failure on take-off (1b5) or cross wind take-off (1b6).	
b	(1) Ground Acceleration Time and Distance.	± 5% or ±1.5 s time and ± 5% or ± 61 m (200 ft) distance	Take-off	CT & M	✓	Acceleration time and distance should be recorded for a minimum of 80% of the total time from brake release to VR. May be combined with normal takeoff (1b4) or rejected takeoff (1b7). Plotted data should be shown using appropriate scales for each portion of the maneuver. For FTD's test limited to time only	

	CLIMB						
	(1) Normal Climb All engines operating	± 3 kts airspeed ± 5% or ± 0.5 m/s (100 ft/min) R/C	Clean or specified climb configuration	~	V	Flight test data or airplane performance manual data may be used. Record at nominal climb speed and mid initial climb altitude. FSTD performance to be recorded over an interval of at least 300 m (1 000 ft). For FTD's may be a Snapshot test	
c	(2) One Engine Inoperative Second Segment Climb	$\pm$ 3 kts airspeed $\pm$ 5% or $\pm$ 0.5 m/s (100 ft/min) R/C but not less than AFM values.	2 <sup>nd</sup> Segment Climb for FNPTs and BITDs Gear up and Take-off Flaps	СТ & М	✓	Flight test data or airplane performance manual data may be used. Record at nominal climb speed. Flight simulator performance to be recorded over an interval of at least 300m (1 000 ft). Test at WAT (Weight, Altitude, or Temperature) limiting condition. For FTD's may be a Snapshot test	
	(3) One Engine Inoperative En route Climb.	± 10% time ± 10% distance ± 10% fuel used	Clean	CT & M	√	Flight test data or airplane performance manual data may be used. Test for at least a 1 550 m (5 000 ft) segment.	



1. P	ERFORMANCE	1						
No	Tosts	Toloronco	Flight	FT	ď	COMMENTS	Res	ult
INO	Tests	Tolerance	Conditions	1	2	COMMENTS	YES	NO
		•						
d	CRUISE/DESCEN	Г						
	(1) Level Flight Acceleration	± 5% time	Cruise	~	✓	Minimum of 50 kts. Increase using maximum continuous thrust rating or equivalent. For very small airplanes, speed change may be reduced to 80% of operational speed range		
	(2) Level Flight Deceleration	± 5% time	Cruise	~	✓	Minimum of 50 kts. decrease using idle power. For very small airplanes, speed change may be reduced to 80% of operational speed range		
	(3) Cruise Performance	$\pm$ 0.05 EPR or $\pm$ 5% N1 or $\pm$ 5% torque $\pm$ 5% fuel flow	Cruise	~	√	May be a single snapshot showing instantaneous fuel flow or a minimum of two consecutive snapshots with a spread of at least 3 minutes in steady flight.		
	(4) Idle Descent	± 3 kts airspeed ± 5% or ± 1.0 m/s (200 ft/min) R/D	Clean			Ide power stabilized descent at normal descent speed at mid altitude. Flight simulator performance to be recorded over an interval of at least 300 m (1 000 ft).		
	(5) Emergency Descent	± 5 kts airspeed ± 5% or ± 1.5 m/s (300 ft/min) R/D	As per AFM			Stabilized descent to be conducted with speed brakes extended if applicable, at mid altitude and near VMO or according to emergency descent procedure. Flight simulator performance to be recorded over an interval of at least 900 m (3 000 ft).		

	e	STOPPING			Not applicable	
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f	ENGINES						
	(1) Acceleration	± 10% Ti or ± 0.25s ± 10% Tt	Approach or Landing	~	~	<ul> <li>Ti = Total time from initial throttle movement until a 10% response of a critical engine parameter.</li> <li>Tt = Total time from initial throttle movement to 90% of go around power. Critical engine parameter should be a measure of power (N1, N2, EPR, etc). Plot from flight idle to go around power for a rapid throttle movement.</li> <li>FTD, FNPT and BITD only: CT&amp;M acceptable.</li> </ul>	



<b>1.</b> P	ERFORMANCE						-	
N.	Testa	Talananaa	Flight	FT	ď	COMMENTS	Res	ult
INO	Tests	Tolerance	Conditions	1	2	COMMENTS	YES	NO
		·						
	(2) Deceleration	± 10% TI or ± 0.25s ± 10% Tt	Ground	~	¥	<ul> <li>Ti = Total time from initial throttle movement Ti = Total time from initial throttle movement until a 10% response of a critical engine parameter.</li> <li>Tt = Total time from initial throttle movement to 90% decay of maximum take-off power.</li> <li>Plot from maximum take-off power to idle for a rapid throttle movement.</li> <li>FTD, FNPT and BITD only: CT&amp;M acceptable.</li> </ul>		

# 2. HANDLING QUALITIES

a	STATIC CONTROL	L CHECKS					
						NOTE: Pitch, roll and yaw controller position vs. force or time shall be measured at the control. An alternative method would be to instrument the FSTD in an equivalent manner to the flight test airplane. The force and position data from this instrumentation can be directly recorded and matched to the airplane data. Such a permanent installation could be used without any time for installation of external devices. CCA: Testing of position versus force is not applicable if forces are generated solely by use of airplane hardware in the FSTD.	
	<ol> <li>Pitch Controller         Position vs. Force             and Surface             Position             Calibration.         </li> </ol>	$\pm$ 0.9 daN (2 lbs) breakout. $\pm$ 2.2 daN (5 lbs) or $\pm$ 10% force. $\pm$ 2° elevator angle	Ground	CT & M	✓	Uninterrupted control sweep to stops. Should be validated (where possible) with in-flight data from tests such as longitudinal static stability, stalls, etc. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures.	
	(2) Roll Controller Position vs. Force and Surface Position Calibration.	$\pm$ 0.9 daN (2 lbs) breakout $\pm$ 1.3 daN (3 lbs) or $\pm$ 10% force $\pm$ 2° aileron angle $\pm$ 3° spoiler angle	Ground	CT & M	~	Uninterrupted control sweep to stops. Should be validated with in-flight data from tests such as engine out trims, steady state sideslips, etc. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures.	



NoTestsToleranceFight ConditionsFTD 1COMMENTSResult VES[3] Rudder Pedal Position vs. Force and Surface Calibration. $\pm 2.2  daN (5  lbs)$ breakout $\pm 2.2  daN (5  lbs)$ or $\pm 10\%$ force $\pm 2^{\circ}$ rudder angleGroundCT $\&$ MUninterrupted control sweep to stops. Should be validated with in flight data for tests sub as engine out trims, steady state sidelips, etc. Static and dynamic flight control tests should be accomplished at the same feel or impact pressuresCT $\checkmark$ V force equivalent(6) Pitch Trim Indicator vs. Surface Position Calibration $\pm 0.5^{\circ}$ trim angle. $\pm 1^{\circ}$ of trim angleGroundVV forund and approachBTD: Only applicable if appropriate trim rate to be checked at pilot primary induced trim rate (7/s)Trim rate to be checked at pilot and autopilot or pilot primary trim rate in fight a goaround flight conditions.(8) Alignment of Lever vs. Selected Engine Parameter. $\pm 9^{\circ}$ of TLA or to $\pm 3\%$ NI or $\pm$ $0.30 EPR or \pm3\% torqueGroundVVVwere the angular travel, auppleable in propeller-drivenairplanes, where thepropeller levers do nothave angular travel, ato era equival travel, auppleable.For airplanes with throtte detents, alldetents to be presented.NoDYNAMIC CONTROL CHECKSVNot andand series of Snaphot tests$	<b>2.</b> H	ANDLING QUALIT	TES						
Image: Note of the series o	No	Tests	Tolorongo	Flight	FT	Ď	COMMENTS	Res	ult
(3) Rudder Pedal Position vs. Force and Surface Position $\pm 2.2$ daN (5 lbs) breakout $\pm 2.2$ daN (5 lbs) or $\pm 10\%$ force $\pm 2^{\circ}$ rudder angleGroundUninterrupted control sweep to stops. Should be validated with in flight data from tests such as engine out trims, steady state sideslips, etc. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures(6) Pitch Trim Indicator vs. Surface Position Calibration $\pm 0.5^{\circ}$ trim angle.GroundPurpose of test is to compare flight simulator against design data or equivalent(7) Pitch Trim Rate Lever vs. Selected Engine Parameter. $\pm 10\%$ or $\pm 0.5$ deg/s trim rate (°/s)Ground and approach $\checkmark$ $\checkmark$ (8) Alignment of Cockpit Throttle Lever vs. Selected Engine Parameter. $\pm 5^{\circ}$ of TLA or $\pm 3^{\circ}$ to rqueGround $\checkmark$ $\checkmark$ For popeller-driven airplanes, where the propeller levers do not have angular travel, a to lerance of $\pm 2$ cm ( $\pm$ $0.3$ EPR or $\pm$ $3^{\circ}$ to rqueGround $\checkmark$ $\checkmark$ For airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked.In the case of propeller-driven angular travel a tolerance of $\pm 2$ cm ( $\pm$ $0.8$ in) applies. $\checkmark$ $\checkmark$ b) DYNAMIC CONTROL CHECKSNot emplicableNot emplicable	INU	1 6815	Toterance	Conditions	1	2	COMMENTS	YES	NO
(3) Rudder Pedal Position vs. Force and Surface Calibration       ± 2.2 daN (5 lbs) breakout ± 2.2 daN (5 lbs) or ± 10% force ± 2.2 rudder angle       Ground       Uninterrupted control sweep to stops. Should be validated with in flight data of the validated with in flight data steady state sideslips, etc. Static and dynamic flight control texts should be accomplished at the same feel or impact pressures         (6) Pitch Trim Indicator vs. Surface Position Calibration       ± 0.5° trim angle. ± 0.5° trim angle. Uninterrupted control texts should be accomplished at the same feel or impact pressures         (7) Pitch Trim Rate       ± 10% or ± 0.5 deg/s trim rate (*/s)       Ground and approach       ✓       BITD: Only applicable if appropriate trim set to be checked at pilot primary induced trim rate (ground) and autopilot primary trim rate in flight at goaround flight conditions.         (8) Alignment of Cockpit Throttle Lever vs. Selected Engine Parameter.       ± 5° of TLA or ± 3% torque       Ground approach       ✓       V         For arplanes, where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.       ✓       ✓       Simultaneous recording in adautiopilot primary trim arplanes, if an additional lever, usually referred to as the propeller-driven argular travel a tolerance of ± 2 cm (± 0.8 inches) applies.         b       DYNAMIC CONTROL CHECKS       Not applicable       Not applicable									
(6) Pitch Trim Indicator       ± 0.5° trim angle.       Ground       Purpose of test is to compare flight simulator against design data or equivalent         Surface Position       ±1° of trim angle       Ground       ✓       BTD: Only applicable if appropriate trim settings are available, e.g. data from the AFM.         (7) Pitch Trim Rate       ±10% or ± 0.5 deg/s trim rate (°/s)       Ground and approach       ✓       ✓         (8) Alignment of       ±5° of TLA or       Ground       ✓       ✓       Trim rate to be checked at pilot primary trim rate in flight agaoround flight conditions.         (8) Alignment of       ±5° of TLA or       Ground       ✓       ✓       Simultaneous recording for all engines. The tolerances apply against airplanes where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.       For airplanes with throttle detents, all detents to be prosented.         0.8 in) applies.       In the case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked.       Where these levers do not have angular travel a tolerance of ± 2 cm (± 0.8 inches) applies.         b       DYNAMIC CONTROL CHECKS       Not applies.       Not applicable		(3) Rudder Pedal Position vs. Force and Surface Position Calibration.	$\pm$ 2.2 daN (5 lbs) breakout $\pm$ 2.2 daN (5 lbs) or $\pm$ 10% force $\pm$ 2° rudder angle	Ground	CT & M	~	Uninterrupted control sweep to stops. Should be validated with in flight data from tests such as engine out trims, steady state sideslips, etc. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures		
Calibration       ±1° of trim angle       Ground       ✓       BTD: Only applicable if appropriate trim settings are available, e.g. data from the AFM.         (7) Pitch Trim Rate       ± 10% or ± 0.5 deg/s trim rate (°/s)       Ground and approach       ✓       ✓       Tim rate to be checked at pilot primary trim rate (ground) and autopilot or pilot primary trim rate in flight at goaround flight conditions.         (8) Alignment of       ± 5° of TLA or       ± 3% NI or ±       Ground       ✓       ✓         (8) Alignment of       ± 5° of TLA or       ± 3% NI or ±       Ground       ✓       ✓         (9) Gox EPR or ±       3% torque       Ground       ✓       ✓       ✓         For propeller-driven airplanes, where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.       ✓       ✓       ✓         (0.8 in) applies.       Ø       Ø       ✓       ✓       ✓       ✓         (8) Alignment of       ± 0° of TLA or       ± 0° of true       ✓       ✓       ✓       ✓         (8) Alignment of       ± 5° of TLA or       ± 3% NI or ±       Ø       Ø       ✓       ✓       ✓         For propeller-driven airplanes, where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.       ✓       ✓       ✓       In the case of propeller-driven airplanes, if an		(6) Pitch Trim Indicator vs. Surface Position	$\pm 0.5^{\circ}$ trim angle.	Ground			Purpose of test is to compare flight simulator against design data or equivalent		
(7) Pitch Trim Rate       ± 10% or ± 0.5 deg/s trim rate (°/s)       Ground and approach       Trim rate to be checked at pilot primary induced trim rate (ground) and autopilot or pilot primary trim rate in flight at goaround flight conditions.         (8) Alignment of Cockpit Throttle Lever vs. Selected Engine Parameter.       ± 5° of TLA or ± 3% NI or ± 0-03 EPR or ± 3% torque       Ground       Simultaneous recording for all engines. The tolerances apply against airplane data and between engines.         For propeller-driven airplanes, where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.       For airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked.         Where these levers do not have angular travel a tolerance of ± 2 cm (± 0.8 inches) applies.       Where these levers do not have angular travel a tolerance of ± 2 cm (± 0.8 inches) applies.		Calibration	±1° of trim angle	Ground	~	~	BITD: Only applicable if appropriate trim settings are available, e.g. data from the AFM.		
<ul> <li>(8) Alignment of Cockpit Throttle ± 5° of TLA or ± 3% N1 or ± Lever vs. Selected Engine Parameter.</li> <li>(8) Alignment of Cockpit Throttle ± 3% N1 or ± 0.03 EPR or ± 3% torque</li> <li>For propeller-driven airplanes, where the propeller levers do not have angular travel, a tolerance of ± 2 cm (± 0.8 in) applies.</li> <li>(1) The case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked.</li> <li>(2) Where these levers do not have angular travel a tolerance of ± 2 cm (± 0.8 in) applies.</li> <li>(3) DYNAMIC CONTROL CHECKS</li> <li>(4) DYNAMIC CONTROL CHECKS</li> <li>(5) Alignment of Cockpit Throttle (5) Simultaneous recording for all engines. The tolerances apply against airplanes with throttle detents, all detents to be presented.</li> <li>(4) The case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked.</li> <li>(4) Where these levers do not have angular travel a tolerance of ± 2 cm (± 0.8 inches) applies.</li> <li>(5) May be a series of Snapshot tests</li> </ul>		(7) Pitch Trim Rate	$\pm$ 10% or $\pm$ 0.5 deg/s trim rate (°/s)	Ground and approach	~	~	Trim rate to be checked at pilot primary induced trim rate (ground) and autopilot or pilot primary trim rate in flight at goaround flight conditions.		
b DYNAMIC CONTROL CHECKS Not applicable		(8) Alignment of Cockpit Throttle Lever vs. Selected Engine Parameter.	$\pm$ 5° of TLA or $\pm$ 3% N1 or $\pm$ 0.03 EPR or $\pm$ 3% torque For propeller-driven airplanes, where the propeller levers do not have angular travel, a tolerance of $\pm$ 2 cm ( $\pm$ 0.8 in) applies.	Ground	×	¥	Simultaneous recording for all engines. The tolerances apply against airplane data and between engines. For airplanes with throttle detents, all detents to be presented. In the case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked. Where these levers do not have angular travel a tolerance of $\pm 2 \text{ cm} (\pm$ 0.8 inches) applies. May be a series of Snapshot tests		
	b	DYNAMIC CONTR	OL CHECKS				Not applicable		

#### **b DYNAMIC CONTROL CHECKS**

c	LONGITUDINAL					Power setting may be that required for level flight unless otherwise specified.	
	(1) Power Change Dynamics.	± 3 kts airspeed ± 30 m (100 ft) altitudes. ± 1.5° or ± 20% pitch angle	Approach	CT & M	*	Power change from thrust for approach or level flight to maximum continuous or go- around power. Time history of uncontrolled free response for a time increment equal to at least 5 sec before initiation of the power change to completion of the power change + 15 sec. CCA: Test in Normal AND Non-normal Control state.	



<b>2.</b> H	2. HANDLING QUALITIES									
No	Tests	Tolerance	Flight	FT	Ď	COMMENTS	Res	ult		
			Conditions	1	2		YES	NO		
	(2) Flap Change Dynamics.	$\pm$ 3 kts airspeed $\pm$ 30 m (100 ft) altitudes. $\pm$ 1.5° or $\pm$ 20% pitch angle	Take-off Through initial flap retraction and approach to landing	CT & M	✓	Time history of uncontrolled free response for a time increment equal to at least 5 sec before initiation of the reconfiguration change to completion of the reconfiguration change + 15 sec. CCA: Test in Normal and Non-normal Control state				
	(3) Spoiler / Speed brake Change Dynamics.	± 3 kts airspeed ± 30 m (100 ft) altitude. ± 1.5 ° or ± 20% pitch angle	Cruise	CT & M	¥	Time history of uncontrolled free response for a time increment equal to at least 5 sec before initiation of the reconfiguration change to completion of the reconfiguration change + 15 sec. Results required for both extension and retraction. CCA: Test in Normal AND Non- normal Control state				
	(4) Gear Change Dynamics.	$\pm$ 3 kts airspeed $\pm$ 30 m (100 ft) altitude. $\pm$ 1.5° or $\pm$ 20% pitch angle For FNPTs and BITDs, $\pm$ 2° or $\pm$ 20% pitch angle	Takeoff (retraction) and Approach (extension)	CT & M	*	Time history of uncontrolled free response for a time increment equal to at least 5 sec before initiation of the configuration change to completion of the reconfiguration change + 15 sec. CCA: Test in Normal AND Non- normal Control state				
	(5) Longitudinal Trim	$\pm$ 1° elevator $\pm$ 0· 5° stabilizer $\pm$ 1° pitch angle $\pm$ 5% net thrust or equivalent	Cruise, Approach and Landing	CT & M	*	Steady-state wings level trim with thrust for level flight. May be a series of snapshot tests. CCA: Test in Normal OR Non-normal Control state.				
	(6) Stall Characteristics.	<ul> <li>± 3 kts airspeed for initial buffet, stall warning, and stall speeds.</li> <li>For airplanes with reversible flight control systems (for FS only):</li> <li>± 10% or ± 2.2 daN (5 lb) column force (prior to g-break only)</li> </ul>	2nd Segment Climb and Approach or Landing	~	~	Wings-level (1 g) stall entry with thrust at or near idle power. Time history data should be shown to include full stall and initiation of recovery. Stall warning signal should be recorded and should occur in the proper relation to stall. FSTDs for airplanes exhibiting a sudden pitch attitude change or 'g break' should demonstrate this characteristic. CCA: Test in Normal and Non-normal Control state.				



<b>2.</b> H	IANDLING QUALIT	TIES						
No	Tosts	Tolerance	Flight	FTD		COMMENTS	Res	ult
110	1 6865	Tolerance	Conditions	1	2	COMMENTS	YES	NO
d	LATERAL DIRECT	ΓIONAL				Power setting may be that required for level flight unless otherwise specified.		
	<ol> <li>Minimum Control Speed, Air (VMCA or VMCL), per Applicable Airworthiness Standard or Low Speed Engine Inoperative Handling Characteristics in the Air.</li> </ol>	± 3 kts airspeed	Take-off or Landing (whichever is most critical in The airplane)	CT & M	*	Minimum speed may be defined by a performance or control limit which prevents demonstration of VMC or VMCL in the conventional manner. Take-off thrust should be set on the operating engine(s). Time history or snapshot data may be used CCA: Test in Normal OR Non-normal Control state.		
	(2) Roll Response (Rate).	$\pm$ 10% or $\pm$ 2% sec roll rate FS only: For airplanes with reversible flight control systems: $\pm$ 10% or $\pm$ 1.3 daN (3 lb) roll controller force.	Cruise and Approach or Landing	CT & M	•	Test with normal roll control displacement (about 30% of maximum control wheel). May be combined with step input of flight deck roll controller test (2d3).		
	(4) Spiral Stability.	Correct trend and ± 2° or ± 10% bank angle in 20 seconds If alternate test is used: correct trend and ± 2° aileron.	Cruise and Approach or Landing	CT & M	•	Airplane data averaged from multiple tests may be used. Test for both directions. As an alternative test, show lateral control required to maintain a steady turn with a bank angle of approximately 30°. CCA: Test in Non-normal Control state.		
	(5) Engine Inoperative Trim.	<ul> <li>± 1° rudder angle or</li> <li>± 1° tab angle or</li> <li>equivalent pedal.</li> <li>± 2° sideslip angle.</li> </ul>	2nd Segment Climb and Approach or Landing	CT & M	*	Test should be performed in a manner similar to that for which a pilot is trained to trim an engine failure condition. 2nd segment climb test should be at take-off thrust. Approach or landing test should be at thrust for level flight. May be snapshot tests.		
<b></b>						NI-4		
e	LANDINGS					Not applicable		
•				1			1	
f	GROUND EFFECT					Not applicable		
g	WIND SHEAR					Not applicable		



<b>2.</b> H	IANDLING QUALIT	TIES						
N	Testa	Telerance Flight		FI	Ď	COMMENTS	Res	ult
NO	1 ests	loierance	Conditions	1	2	COMMENTS	YES	NO
h	Flight And Maneuve	er Envelope Protectio	n Functions					
						This paragraph is only applicable to Computer-controlled airplanes. Time history results of response to control inputs during entry into each envelope protection function (i.e., with normal and degraded control states if function is different) are required. Set thrusts as required to reach the envelope protection function		
	(1) Over speed	± 5 kts airspeed	Cruise	~	~			
	(2) Load Factor	± 0.1 g	Take-off, Cruise	~	~			
	(3) Pitch Angle	± 1.5° pitch angle	Cruise, Approach	~	~			
	(4) Bank Angle	± 2° or ± 10% bank angle	Approach	~	~			
	(5) Angle of Attack	± 1.5° AOA	Second Segment Climb and Approach or Landing	~	✓			

# **3. MOTION SYSTEM**

# Not applicable

## 4. VISUAL SYSTEM

a	SYSTEM RESPONS	SE TIME					
	(1) Transport Delay	150 milliseconds or less after controller movement.	Pitch, roll and yaw	$\checkmark$	V	One separate test is required in each axis. See GACAR PART 60- FSTD	
		after controller movement.					
	or						
	(2) Latency	<ul> <li>150</li> <li>milliseconds or less after controller</li> <li>movement.</li> <li>300 milliseconds or less after controller</li> <li>movement</li> </ul>	Take-off, Cruise, and Approach or Landing	~	~	One test is required in each axis (pitch, roll, yaw) for each of the 3 conditions compared with airplane data for a similar input. The visual scene or test pattern used during the response testing shall be representative of the required system capacities to meet the daylight, twilight (dusk/dawn) and night visual capability as applicable.	



4. V	ISUAL SYSTEM							
No	No Testa Toloropeo Flight FTD COM		COMMENTS	Result				
INO	Tests	Tolerance	Conditions	1	2	COMMENTS	YES	NO
	(3) Light point Contrast Ratio	Not less than 10:1	Not Applicable	~		Light point contrast ratio should be measured using a test pattern demonstrating a 1° area filled with light points (i.e. light point modulation just discernible) and should be compared to the adjacent background.		
		Not less than 25:1				Note. During contrast ratio testing, simulator aft-cab and flight deck ambient light levels should be zero.		

## 5. SOUND SYSTEMS

Not applicable

Rema	urks		

Inspector Name	Date	Signature

Qualified FTD (	) Assessor Name	Date	Signature